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Latent Consistency Models - Synthesizing High-Resolution Images with Few-Step Inference

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Artificial Intelligence

Creating the Future

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References

Simian Luo, Yiqin Tan, Longbo Huang, Jian Li, Hang Zhao Latent Consistency Models: Synthesizing High-Resolution Images with Few-Step Inference arXiv:2310.04378

https://latent-consistency-models.github.io/ https://github.com/luosiallen/latent-consistency-model

huggingface

https://huggingface.co/docs/diffusers/api/pipelines/latent_consistency_ models https://huggingface.co/SimianLuo/LCM Dreamshaper v7

[Paper Review blog] https://kimjy99.github.io/논문리뷰/latent-consistency-model/ http://dmqm.korea.ac.kr/activity/seminar/434 Accelerating Diffusion Models: Consistency Models and Hybrid Approach https://www.youtube.com/watch?v=OT3JWNz0II8&t=235s

Abstract (Paper)

- Latent Diffusion models (LDMs)
 - ✓ Remarkable results in synthesizing high-resolution images.
 - However, Iterative sampling process Computationally intensive and leads to slow generation.
- Inspired by Consistency Models (song et al.),
- · Propose Latent Consistency Models (LCMs),
 - Enabling swift Inference with minimal steps on any pre-trained LDMs, including Stable Diffusion (rombach et al).
- Viewing the guided reverse diffusion process as solving an augmented probability flow ODE (PF-ODE),
- LCMs are designed to directly predict the solution of such ODE in latent space, mitigating the need for numerous iterations and allowing rapid, high-fidelity sampling.

- Efficiently distilled from pre-trained classifier-free guided diffusion models, a high-quality 768 x 768 2~4-step LCM takes only 32 A100 GPU hours for training.
- Furthermore, introduce Latent Consistency Fine-tuning (LCF), a novel method that is tailored for fine-tuning LCMs on customized image datasets.
- Evaluation on the LAION-5B-Aesthetics dataset demonstrates that LCMs achieve **state-of-the-art text-to-image generation** performance with **few-step inference**.
- Project Page: https://latent-consistency-models.github.io/

https://latent-consistency-models.github.io/



4-Steps Inference

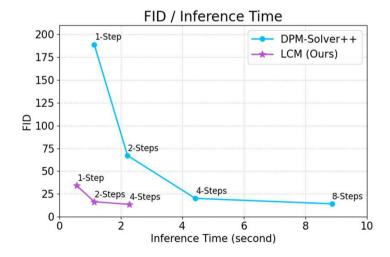
Few-Step Generated Images :

LCMs can be distilled from any pre-trained Stable Diffusion (SD) in only 4,000 training steps (~32 A100 GPU Hours) for generating high quality 768 x 768 resolution images in 2~4 steps or even one step, significantly accelerating text-to-image generation. We employ LCM to distill the Dreamshaper-V7 version of SD in just 4,000 training iterations.



2-Steps Inference

1-Step Inference



1 Introduction & 2. Related Works

Diffusion Models

- Compared to VAEs and GANs, diffusion models enjoy the benefit of training stability and better likelihood estimation.
- Be trained to denoise the noise-corrupted data to estimate the score of data distribution.
- During inference, draw samples by running the reverse diffusion process to gradually denoise the data point.
- · Bottlenecked by their slow generation speed
- Ho et al., 2020, **DDPM**, Denoising Diffusion Probabilistic Models
- Song et al., 2020a, **DPIM**, Denoising Diffusion Implicit Models
- Nichol & Dhariwal, 2021, **iDDPM**, Improved Denoising Diffusion Probabilistic Models
- Ramesh et al., 2022, **DALL-E2**, Hierarchical Text-Conditional Image Generation with Clip Latents
- Rombach et al., 2022, **Stable Diffusion**, High-Resolution Image Synthesis with Latent Diffusion Models
- Song & Ermon, 2019. Generative Modeling by Estimating Gradients of the Data Distribution

Accelerating DMs

○ Training-free methods such as

- ODE solvers : Song et al., 2020a, DPIM; Lu et al., 2022a;b, DPM-Solver, DPM-Solver++
- Adaptive step size solvers : Jolicoeur-Martineau et al., 2021, Gotta go fast when generating data with score-based models.
- **Predictor-corrector methods** : Song et al., 2020b, Score-based generative modeling through stochastic differential equations

○ Training-based approaches include

- **Optimized discretization** : Watson et al., 2021, Learning to efficiently sample from diffusion probabilistic models
- Truncated diffusion : Lyu et al., 2022; Zheng et al., 2022,
- **Neural operator** : Zheng et al., 2023, Fast sampling of diffusion models via operator learning
- Distillation : Salimans & Ho, 2022, Progressive distillation for fast sampling of diffusion models; Meng et al., 2023, On distillation of guided diffusion models
- More recently, new generative models for faster sampling have also been proposed (Liu et al., 2022; 2023).

1 Introduction & 2. Related Works

Latent Diffusion Models (LDMs)

- · Synthesizing high-resolution text-to-images.
- Ex) Stable Diffusion (SD) performs forward and reverse diffusion processes in the data latent space, resulting in more efficient computation.
- Rombach et al., 2022, **Stable Diffusion**, High-Resolution Image Synthesis with Latent Diffusion Models

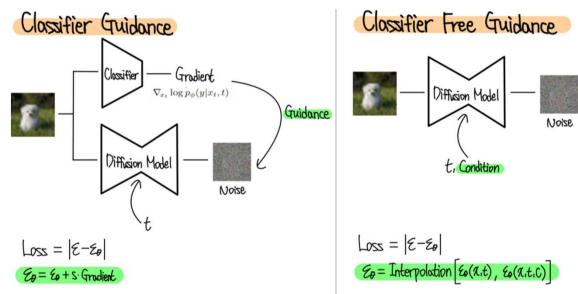
Consistency Models (CMs)

- A new type of generative model for **faster sampling** while **preserving generation quality**.
- CMs adopt consistency mapping to directly map any point in ODE trajectory to its origin, enabling fast one-step generation.
- CMs can be **trained by distilling pre-trained diffusion models** or as standalone **generative models**.
- Song et al., 2023, Consistency Models
- CMs constrained to pixel space image generation tasks, making it unsuitable for synthesizing high-resolution images.
- Moreover, the applications to the conditional diffusion model and the incorporation of classifier-free guidance have not been explored, rendering their methods unsuitable for text-to-image generation synthesis.

1 Introduction & 2. Related Works

Classifier Free Guidance : Classifier-free diffusion guidance

- Jonathan Ho, Tim Salimans, Classifier-Free Diffusion Guidance, NIPS2021, Google Research, Brain team
- Diffusion Models Beat GANs on Image Synthesis 논문:
 - ✓ 추가 classifier를 학습하여 샘플의 품질을 향상시키는 classifier guidance가 제안됨. Classifier guidance는 diffusion model의 score 추정치와 classifier의 로그 확률의 입력 기울기를 혼합함.
 - ✓ Classifier gradient의 강도를 변경하여 Inception Score (IS)와 FID (또 는 precision과 recall)를 절충할 수 있음
- 어떠한 classifier도 사용하지 않는 classifier-free guidance를 제안함
- Classifier-free guidance는 이미지 classifier의 기울기 방향으로 샘플링 하는 대신 conditional diffusion model과 함께 학습된 unconditional diffusion model의 score 추정치를 혼합함.
- 혼합 가중치를 사용하여 classifier guidance에서 얻은 것과 유사한 FID/IS tradeoff를 얻는다. 또한 pure generative diffusion model이 다른 유형의 생성 모델과 함께 매우 높은 fidelity의 샘플을 합성하는 것이 가능함



[Source] https://ffighting.net/deep-learning-paper-review/diffusionmodel/classifier-free-guidance/

Main Contributions

- Latent Consistency Models (LCMs) for fast, high-resolution image generation.
 - LCMs employ consistency models in the image latent space, enabling fast few-step or even one-step high-fidelity sampling on pre-trained latent diffusion models (e.g., Stable Diffusion (SD)).
- Provide a simple and efficient one-stage guided consistency distillation method
 - to distill SD for few-step (2~4) or even 1-step sampling
 - to efficiently convert a pre-trained guided diffusion model into a latent consistency model by solving an augmented PF-ODE.
 - Propose the *SKIPPING-STEP* technique to further accelerate the convergence.
 - For 2- and 4-step inference, our method costs only 32 A100 GPU hours for training and achieves state-of-the-art performance

O Propose Latent Consistency Finetuning, which allows fine-tuning a pre-trained LCM to support few-step inference on customized image datasets while preserving the ability of fast inference.

3. PRELIMINARIES

***** Diffusion Models

- Diffusion models, or score-based generative models
- Progressively inject Gaussian noises into the data, and then generate samples from noise via a reverse denoising process
- Define a **forward process** transitioning the origin data distribution $p_{data}(x)$ to marginal distribution $q_t(x_t)$, via transition kernel:

$$q_{0t}(\boldsymbol{x}_t|\boldsymbol{x}_0) = N(\boldsymbol{x}_t|\boldsymbol{\alpha}(t)\boldsymbol{x}_0, \sigma^2(t)\boldsymbol{I}),$$

- $\alpha(t)$, $\sigma(t)$ specify the noise schedule.
- O In continuous time perspective, the forward process can be described by a stochastic differential equation (SDE) for t ∈ [0, T]: (I Song et al. (2020b); Lu et al. (2022a); Karras et al. (2022))

$$d\mathbf{x}_t = f(t)\mathbf{x}_t dt + g(t)d\mathbf{w}_t, \qquad \mathbf{x}_0 \sim p_{data}(\mathbf{x}_0)$$

• w(t) is the standard Brownian motion

$$f(t) = \frac{\mathrm{d}\log\alpha(t)}{\mathrm{d}t}, \quad g^2(t) = \frac{\mathrm{d}\sigma^2(t)}{\mathrm{d}t} - 2\frac{\mathrm{d}\log\alpha(t)}{\mathrm{d}t}\sigma^2(t).$$
(1)

- \bigcirc By considering the reverse time SDE,
 - the marginal distribution q_t(x) satisfies the following ordinary differential equation, called the **Probability Flow ODE (PF-ODE)** (
 Song et al., 2020b; Lu et al., 2022a):

$$\frac{\mathrm{d}\boldsymbol{x}_{t}}{\mathrm{d}t} = f(t)\boldsymbol{x}_{t} - \frac{1}{2}g^{2}(t)\nabla_{\boldsymbol{x}}\log q_{t}\left(\boldsymbol{x}_{t}\right), \ \boldsymbol{x}_{T} \sim q_{T}\left(\boldsymbol{x}_{T}\right).$$
(2)

- In diffusion models, we train the noise prediction model $\epsilon_{\theta}(x_t, t)$ to fit $-\nabla \log q_t(x_t)$ (called the *score function*).
 - Approximating the score function by the noise prediction model in 21, one can obtain the following **empirical PF-ODE** for sampling:

$$\frac{\mathrm{d}\boldsymbol{x}_{t}}{\mathrm{d}t} = f(t)\boldsymbol{x}_{t} + \frac{g^{2}(t)}{2\sigma_{t}}\boldsymbol{\epsilon}_{\theta}\left(\boldsymbol{x}_{t}, t\right), \quad \boldsymbol{x}_{T} \sim \mathcal{N}\left(\boldsymbol{0}, \tilde{\sigma}^{2}\boldsymbol{I}\right).$$
(3)

9

3. PRELIMINARIES

***** Diffusion Models

- For class-conditioned diffusion models,
 - Classifier-Free Guidance (CFG) (Ho & Salimans, 2022) :
 - An effective technique to significantly improve the quality of generated samples
 - ✓ Has been widely used in several large-scale diffusion models including GLIDE Nichol et al. (2021), Stable Diffusion (Rombach et al., 2022), DALL·E 2 (Ramesh et al., 2022) and Imagen (Saharia et al., 2022).
 - Given a CFG scale ω, the original noise prediction is replaced by a linear combination of conditional and unconditional noise prediction:

 $\tilde{\boldsymbol{\epsilon}}_{\boldsymbol{\theta}}(\boldsymbol{z}_t, \boldsymbol{\omega}, \boldsymbol{c}, t) = (1 + \boldsymbol{\omega})\boldsymbol{\epsilon}_{\boldsymbol{\theta}}(\boldsymbol{z}_t, \boldsymbol{c}, t) - \boldsymbol{\omega}\boldsymbol{\epsilon}_{\boldsymbol{\theta}}(\boldsymbol{z}, \boldsymbol{\varnothing}, t)$

3. PRELIMINARIES

Consistency Models

- A new family of generative models
 - Enables one-step or few-step generation.
 - Core idea : Learn the consistency function that maps any points on a trajectory of the PF-ODE to that trajectory's origin (i.e., the solution of the PF-ODE)

$$oldsymbol{f}\,:\,(oldsymbol{x}_t,t)\,\longmapsto\,oldsymbol{x}_\epsilon$$

 ϵ is a fixed small positive number.

 The consistency function should satisfy the *self-consistency* property:

$$\boldsymbol{f}(\boldsymbol{x}_t, t) = \boldsymbol{f}(\boldsymbol{x}_{t'}, t'), \forall t, t' \in [\epsilon, T].$$
(4)

- (Song et al., 2023) Key idea for learning a consistency model f_{θ} : To learn a consistency function from data by effectively enforcing the self-consistency property
- Ensure that *f*_θ(*x*, ε) = *x*, the consistency model *f*_θ is parameterized as:

$$f_{\theta}(\boldsymbol{x},t) = c_{\text{skip}}(t)\boldsymbol{x} + c_{\text{out}}(t)F_{\theta}(\boldsymbol{x},t),$$
(5)

 $c_{skip}(t)$ and $c_{out}(t)$: Differentiable functions with $c_{skip}(t,\epsilon) = 1$ and $c_{out}(\epsilon) = 0$

 $F_{\theta}(x, t)$: a deep neural network

• A CM can be either distilled from a pre-trained diffusion model (known as *Consistency Distillation*) or trained from scratch

3. PRELIMINARIES

Consistency Models

- To enforce the self-consistency property, we maintain a target model θ⁻, updated with exponential moving average (EMA) of the parameter θ, we intend to learn; θ⁻ ← μθ⁻ + (1 − μ)θ
- Define the consistency loss

$$\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\theta}^{-}; \Phi) = \mathbb{E}_{\boldsymbol{x}, t} \left[d \left(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{x}_{t_{n+1}}, t_{n+1}), \boldsymbol{f}_{\boldsymbol{\theta}^{-}}(\hat{\boldsymbol{x}}_{t_{n}}^{\boldsymbol{\phi}}, t_{n}) \right) \right], \quad (6)$$

 $d(\cdot)$: a chosen metric function for measuring the distance between two samples; $d(x, y) = ||x - y||^2$

 $\hat{x}_{t_n}^{\phi}$: a one-step estimation of x_{t_n} from $x_{t_{n+1}}$

$$\hat{x}_{t_n}^{\phi} \leftarrow x_{t_{n+1}} + (t_n - t_{n+1}) \Phi(x_{t_{n+1}}, t_{n+1}; \phi).$$
(7)

 Φ denotes the one-step ODE solver applied to PF-ODE in Eq. 24. (Song et al., 2023) used Euler (Song et al., 2020b) or Heun solver (Karras et al., 2022) as the numerical ODE solver Pseudo-code for consistency distillation

Algorithm 2 Consistency Distillation (CD) (Song et al., 2023)

Input: dataset \mathcal{D} , initial model parameter θ , learning rate η , ODE solver $\Phi(\cdot, \cdot, \cdot)$, distance metric $d(\cdot, \cdot)$, and EMA rate μ

$heta^- \leftarrow heta$ repeat

Sample
$$\boldsymbol{x} \sim \mathcal{D}$$
 and $n \sim \mathcal{U}[1, N-1]$
Sample $\boldsymbol{x}_{t_{n+1}} \sim \mathcal{N}(\boldsymbol{x}; t_{n+1}^2 \mathbf{I})$
 $\hat{\boldsymbol{x}}_{t_n}^{\phi} \leftarrow \boldsymbol{x}_{t_{n+1}} + (t_n - t_{n+1})\Phi(\boldsymbol{x}_{t_{n+1}}, t_{n+1}, \phi)$
 $\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\theta}^-; \Phi) \leftarrow d(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{x}_{t_{n+1}}, t_{n+1}), \boldsymbol{f}_{\boldsymbol{\theta}^-}(\hat{\boldsymbol{x}}_{t_n}^{\phi}, t_n))$
 $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \eta \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\theta}^-; \Phi)$
 $\boldsymbol{\theta}^- \leftarrow \text{stopgrad}(\mu \boldsymbol{\theta}^- + (1-\mu)\boldsymbol{\theta})$
until convergence

4. LATENT CONSISTENCY MODELS

* Summary

Consistency Models (CMs) (Song et al., 2023)

- Only focused on image generation tasks on ImageNet 64×64 (Deng et al., 2009) and LSUN 256×256 (Yu et al., 2015).
- Unexplore to generate higher-resolution text-to-image tasks

Latent Consistency Models (LCMs)

- Adopt a **consistency model** in **the image latent space**, similar to LDMs
- Choose the **Stable Diffusion (SD)** as the underlying diffusion model to **distill** from.
- Aim to achieve few-step (2~4) and even one-step inference on SD without compromising image quality.
- The classifier-free guidance (CFG) (Ho & Salimans, 2022) is an effective technique to further improve sample quality and is widely used in SD.

- Propose a simple one-stage guided distillation method in Sec 4.2 that solves an augmented PF-ODE, integrating CFG into LCM effectively.
- Propose **SKIPPING-STEP** technique to accelerate the convergence of LCMs in Sec. 4.3.
- Finally, propose Latent Consistency Fine-tuning to finetune a pretrained LCM for few-step inference on a customized dataset in Sec 4.4.

4.1 LCM : Consistency Distillation in the Latent Space

- LDM : Stable Diffusion (SD) Image Latent Space (Rombach et al., 2022)
- Utilizing **image latent space** in large-scale diffusion models has effectively **enhanced image generation quality** and **reduced computational load**.
- SD
 - An autoencoder (E, D) is first trained to compress high-dim image data into low-dim latent vector z = E(x), which is then decoded to reconstruct the image as x = D(z).
 - **Training diffusion models in the latent space** greatly reduces the computation costs compared to pixel-based models and speeds up the inference process;
- LDMs make it possible to generate high-resolution images on laptop GPUs.

- For LCMs, we leverage the advantage of the latent space for consistency distillation, contrasting with the pixel space used in CMs (Song et al., 2023).
- Termed Latent Consistency Distillation (LCD) is applied to pretrained SD, allowing the synthesis of high-resolution (e.g., 768×768) images in 1~4 steps.
- We focus on conditional generation.

4.1 LCM : Consistency Distillation in the Latent Space

Recall that the PF-ODE of the reverse diffusion process (Song et al., 2020b; Lu et al., 2022a)

$$\frac{\mathrm{d}\boldsymbol{z}_{t}}{\mathrm{d}t} = f(t)\boldsymbol{z}_{t} + \frac{g^{2}(t)}{2\sigma_{t}}\boldsymbol{\epsilon}_{\theta}\left(\boldsymbol{z}_{t}, \boldsymbol{c}, t\right), \quad \boldsymbol{z}_{T} \sim \mathcal{N}\left(\boldsymbol{0}, \tilde{\sigma}^{2}\boldsymbol{I}\right), \quad (8)$$

- z_t are image latents
- $\epsilon_{\theta}(z_t, c, t)$ is the noise prediction model
- *c* is the given condition (e.g text)
- Samples can be drawn by solving the PF-ODE from *T* to 0.

- > To perform LCD, introduce the consistency function $f_{\theta}: (z_t, c, t) \mapsto z_0$ to directly predict the solution of PF-ODE (Eq. 8) for t = 0.
- We parameterize f_{θ} by the noise prediction model $\hat{\epsilon}_{\theta}$,

$$f_{\theta}(\boldsymbol{z}, \boldsymbol{c}, t) = c_{\text{skip}}(t)\boldsymbol{z} + c_{\text{out}}(t) \left(\frac{\boldsymbol{z} - \sigma_t \hat{\boldsymbol{\epsilon}}_{\theta}(\boldsymbol{z}, \boldsymbol{c}, t)}{\alpha_t}\right), \quad (\boldsymbol{\epsilon}\text{-Prediction}) \quad (9)$$

-
$$c_{skip}(0) = 1$$
 and $c_{out}(0) = 0$

- $\hat{\epsilon}_{\theta}(z_t, c, t)$: a noise prediction model that initializes with the same parameters as the teacher diffusion model
- f_{θ} can be parameterized in various ways, depending on the teacher diffusion model parameterizations of predictions is Appendix D.

4.1 LCM : Consistency Distillation in the Latent Space

> Recall that the **PF-ODE** of the reverse diffusion process

$$\frac{\mathrm{d}\boldsymbol{z}_{t}}{\mathrm{d}t} = f(t)\boldsymbol{z}_{t} + \frac{g^{2}(t)}{2\sigma_{t}}\boldsymbol{\epsilon}_{\theta}\left(\boldsymbol{z}_{t}, \boldsymbol{c}, t\right), \quad \boldsymbol{z}_{T} \sim \mathcal{N}\left(\boldsymbol{0}, \tilde{\sigma}^{2}\boldsymbol{I}\right), \quad (8)$$

- Assume that an efficient ODE solver Ψ(z_t, t, s, c) is available for approximating the integration of the right-hand side of Eq (8) from time t to s.
- In practice, we can use DDIM (Song et al., 2020a), DPM-Solver (Lu et al., 2022a) or DPM-Solver++ (Lu et al., 2022b) as Ψ(·, ·, ·, ·).
- Note that we only use these solvers in training/distillation, not in inference
- Discuss these solvers further when we introduce the SKIPPING-STEP technique in Sec. 4.3

LCM aims to predict the solution of the PF-ODE by minimizing the consistency distillation loss (Song et al., 2023):

$$\mathcal{L}_{\mathcal{CD}}\left(\boldsymbol{\theta},\boldsymbol{\theta}^{-};\boldsymbol{\Psi}\right) = \mathbb{E}_{\boldsymbol{z},c,n}\left[d\left(f_{\boldsymbol{\theta}}(\boldsymbol{z}_{t_{n+1}},c,t_{n+1}),f_{\boldsymbol{\theta}^{-}}(\hat{\boldsymbol{z}}_{t_{n}}^{\boldsymbol{\Psi}},c,t_{n})\right)\right]$$
(10)

• $\hat{z}_{t_n}^{\Psi}$: an estimation of the evolution of the PF-ODE from $t_{n+1} \rightarrow t_n$ using ODE solver Ψ :

$$\hat{\boldsymbol{z}}_{t_n}^{\Psi} - \boldsymbol{z}_{t_{n+1}} = \int_{t_{n+1}}^{t_n} \left(f(t) \boldsymbol{z}_t + \frac{g^2(t)}{2\sigma_t} \boldsymbol{\epsilon}_{\theta} \left(\boldsymbol{z}_t, \boldsymbol{c}, t \right) \right) \mathrm{d}t \qquad (11)$$
$$\approx \Psi(\boldsymbol{z}_{t_{n+1}}, t_{n+1}, t_n, \boldsymbol{c}),$$

 The solver Ψ(·, ·, ·, ·) is used to approximate the integration from t_{n+1}→t_n.

4.2 One-Stage Guided Distillation by Solving Augmented PF-ODE

- Classifier-free guidance (CFG) (Ho & Salimans, 2022)
- Crucial for synthesizing high-quality textaligned images in SD, typically needing a CFG scale ω over 6. Thus, integrating CFG into a distillation method becomes indispensable.
- Previous method Guided-Distill (Meng et al., 2023) introduces a two-stage distillation to support few-step sampling from a guided diffusion model. However, it is computationally intensive (e.g. at least 45 A100 GPUs Days for 2-step inference, estimated in (Liu et al., 2023)).
- An LCM demands merely 32 A100 GPUs Hours training for 2-step inference, as depicted in Figure 1.
- Furthermore, the **two-stage guided distillation** might result in **accumulated error**, leading to suboptimal performance.
- LCMs adopt efficient one-stage guided distillation by solving an augmented PF-ODE.

CFG used in reverse diffusion process

$$\tilde{\boldsymbol{\epsilon}}_{\theta}\left(\boldsymbol{z}_{t},\omega,\boldsymbol{c},t\right) := (1+\omega)\boldsymbol{\epsilon}_{\theta}\left(\boldsymbol{z}_{t},\boldsymbol{c},t\right) - \frac{\omega}{\omega}\boldsymbol{\epsilon}_{\theta}\left(\boldsymbol{z}_{t},\varnothing,t\right), \quad (12)$$

- The original noise prediction is replaced by the linear combination of conditional and unconditional noise
- ω is called the *guidance scale*

Augmented PF-ODE

• To sample from the guided reverse process, we need to solve the following augmented PF-ODE: (i.e., augmented with the terms related to ω)

$$\frac{\mathrm{d}\boldsymbol{z}_{t}}{\mathrm{d}t} = f(t)\boldsymbol{z}_{t} + \frac{g^{2}(t)}{2\sigma_{t}} \tilde{\boldsymbol{\epsilon}}_{\theta}\left(\boldsymbol{z}_{t}, \boldsymbol{\omega}, \boldsymbol{c}, t\right), \quad \boldsymbol{z}_{T} \sim \mathcal{N}\left(\boldsymbol{0}, \tilde{\sigma}^{2}\boldsymbol{I}\right).$$
(13)

4.2 One-Stage Guided Distillation by Solving Augmented PF-ODE

> Augmented consistency function f_{θ}

• To efficiently perform **one-stage guided distillation**, we introduce an augmented consistency function

$$f_{\boldsymbol{ heta}}$$
 : $(\boldsymbol{z_t}, \omega, \boldsymbol{c}, t) \mapsto \boldsymbol{z_0}$

to directly predict the solution of augmented PF-ODE (Eq. 13) for t = 0.

 We parameterize the *f_θ* in the same way as in Eq. 9, except that *ĉ_θ(z_t, c, t)* is replaced by *ĉ_θ(z_t, ω, c, t)*, which is a noise prediction model initializing with the same parameters as the teacher diffusion model, but also contains additional trainable parameters for conditioning on *ω*.

• The **consistency loss** is the same as Eq. 10 except that we use augmented consistency function $f_{\theta}(z_t, \omega, c, t)$.

$$\mathcal{L}_{\mathcal{CD}}\left(\boldsymbol{\theta},\boldsymbol{\theta}^{-};\Psi\right) = \mathbb{E}_{\boldsymbol{z},\boldsymbol{c},\boldsymbol{\omega},\boldsymbol{n}}\left[d\left(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{z}_{t_{n+1}},\boldsymbol{\omega},\boldsymbol{c},t_{n+1}),\boldsymbol{f}_{\boldsymbol{\theta}^{-}}(\hat{\boldsymbol{z}}_{t_{n}}^{\Psi,\boldsymbol{\omega}},\boldsymbol{\omega},\boldsymbol{c},t_{n})\right)\right]$$
(14)

4.2 One-Stage Guided Distillation by Solving Augmented PF-ODE

Consistency Loss

 The consistency loss is the same as Eq. 10 except that we use augmented consistency function *f*_θ(*z*_t, ω, *c*, *t*).

$$\mathcal{L}_{\mathcal{CD}}\left(\boldsymbol{\theta},\boldsymbol{\theta}^{-};\Psi\right) = \mathbb{E}_{\boldsymbol{z},\boldsymbol{c},\boldsymbol{\omega},n}\left[d\left(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{z}_{t_{n+1}},\boldsymbol{\omega},\boldsymbol{c},t_{n+1}),\boldsymbol{f}_{\boldsymbol{\theta}^{-}}(\hat{\boldsymbol{z}}_{t_{n}}^{\Psi,\boldsymbol{\omega}},\boldsymbol{\omega},\boldsymbol{c},t_{n})\right)\right]$$
(14)

- ω and *n* are uniformly sampled from interval [$\omega_{\min}, \omega_{\max}$] and {1, . . . , N-1} respectively.
- $\hat{z}_{t_n}^{\Psi,\omega}$ is estimated using the new noise model $\hat{\epsilon}_{\theta}(z_t, \omega, c, t)$

$$\hat{\boldsymbol{z}}_{t_{n}}^{\Psi,\omega} - \boldsymbol{z}_{t_{n+1}} = \int_{t_{n+1}}^{t_{n}} \left(f(t)\boldsymbol{z}_{t} + \frac{g^{2}(t)}{2\sigma_{t}} \tilde{\boldsymbol{\epsilon}}_{\theta}\left(\boldsymbol{z}_{t},\omega,\boldsymbol{c},t\right) \right) \mathrm{d}t$$

$$= (1+\omega) \int_{t_{n+1}}^{t_{n}} \left(f(t)\boldsymbol{z}_{t} + \frac{g^{2}(t)}{2\sigma_{t}} \boldsymbol{\epsilon}_{\theta}\left(\boldsymbol{z}_{t},\boldsymbol{c},t\right) \right) \mathrm{d}t - \omega \int_{t_{n+1}}^{t_{n}} \left(f(t)\boldsymbol{z}_{t} + \frac{g^{2}(t)}{2\sigma_{t}} \boldsymbol{\epsilon}_{\theta}\left(\boldsymbol{z}_{t},\boldsymbol{c},t\right) \right) \mathrm{d}t - \omega \int_{t_{n+1}}^{t_{n}} \left(f(t)\boldsymbol{z}_{t} + \frac{g^{2}(t)}{2\sigma_{t}} \boldsymbol{\epsilon}_{\theta}\left(\boldsymbol{z}_{t},\boldsymbol{\varnothing},t\right) \right) \mathrm{d}t \qquad (15)$$

$$\approx (1+\omega)\Psi(\boldsymbol{z}_{t_{n+1}},t_{n+1},t_{n},\boldsymbol{c}) - \omega\Psi(\boldsymbol{z}_{t_{n+1}},t_{n+1},t_{n},\boldsymbol{\varnothing}).$$

We can use DDIM (Song et al., 2020a), DPM-Solver (Lu et al., 2022a) or DPM-Solver++ (Lu et al., 2022b) as the PF-ODE solver Ψ(·, ·, ·, ·).

4.3 Accelerating Distillation with Skipping Time Steps

Discretization Schedule (or Time Schedule)

 Discrete diffusion models (Ho et al., 2020; Song & Ermon, 2019) typically train noise prediction models with a long time-step schedule {t_i}_i (also called discretization schedule or time schedule) to achieve high quality generation results.

✓ Stable Diffusion (SD) has a time schedule of length 1,000.

- Directly applying Latent Consistency Distillation (LCD) to SD with such an extended schedule can be problematic.
 - ✓ The model needs to **sample across all 1,000 time steps**.
 - ✓ The consistency loss attempts to aligns the prediction of LCM model $f_{\theta}(z_{t_{n+1}}, c, t_{n+1})$ with the prediction $f_{\theta}(z_{t_n}, c, t_n)$ at the subsequent step along the same trajectory.
 - ✓ Since $t_n t_{n+1}$ is tiny, z_{t_n} and $z_{t_{n+1}}$ (and thus $f_{\theta}(z_{t_{n+1}}, c, t_{n+1})$ and $f_{\theta}(z_{t_n}, c, t_n)$) are already close to each other, incurring small consistency loss and hence leading to slow convergence.

> Skipping-Step

- To address this issues, we introduce the SKIPPING-STEP method to considerably shorten the length of time schedule (from thousands to dozens) to achieve fast convergence while preserving generation quality
- Consistency Models (CMs) (Song et al., 2023)
 - ✓ Use the EDM (Karras et al., 2022) continuous time schedule, and the Euler, or Heun Solver as the numerical continuous PF-ODE solver.
- For LCMs, in order to adapt to the discrete-time schedule in SD,
 - ✓ We utilize DDIM (Song et al., 2020a), DPM-Solver (Lu et al., 2022a), or DPM-Solver++ (Lu et al., 2022b) as the ODE solver. (Lu et al., 2022a) shows that these advanced solvers can solve the PF-ODE efficiently in Eq. 8.

4.3 Accelerating Distillation with Skipping Time Steps

Skipping-Step Method in Latent Consistency Distillation (LCD)

- Instead of ensuring consistency between adjacent time steps *t_{n+1}* → *t_n*, LCMs aim to ensure consistency between the current time step and *k*-step away, *t_{n+k}* → *t_n*.
- SKIPPING-STEP method is crucial in accelerating the LCD process.
- k = 1 reduces to the original schedule in (Song et al., 2023), leading to slow convergence, and very large k may incur large approximation errors of the ODE solvers.
- In our main experiments, we set k = 20, drastically reducing the length of time schedule from thousands to dozens.
- Consistency distillation loss in Eq. 14 is modified to ensure consistency from t_{n+k} to t_n :

$$\mathcal{L}_{\mathcal{CD}}\left(\boldsymbol{\theta},\boldsymbol{\theta}^{-};\Psi\right) = \mathbb{E}_{\boldsymbol{z},\boldsymbol{c},\omega,n}\left[d\left(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{z}_{t_{n+k}},\omega,\boldsymbol{c},t_{n+k}),\boldsymbol{f}_{\boldsymbol{\theta}^{-}}(\hat{\boldsymbol{z}}_{t_{n}}^{\Psi,\omega},\omega,\boldsymbol{c},t_{n})\right)\right]$$
(16)

 $\hat{z}_{t_n}^{\psi,\omega}$ being an estimate of z_{t_n} using numerical **augmented PF-ODE** solver Ψ

$$\hat{\boldsymbol{z}}_{t_n}^{\Psi,\omega} \longleftarrow \boldsymbol{z}_{t_{n+k}} + (1+\omega)\Psi(\boldsymbol{z}_{t_{n+k}}, \boldsymbol{t}_{n+k}, \boldsymbol{t}_n, \boldsymbol{c}) - \omega\Psi(\boldsymbol{z}_{t_{n+k}}, \boldsymbol{t}_{n+k}, \boldsymbol{t}_n, \boldsymbol{\varnothing})$$
(17)

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$$\hat{\boldsymbol{z}}_{t_n}^{\Psi,\omega} \longleftarrow \boldsymbol{z}_{t_{n+k}} + (1+\omega)\Psi(\boldsymbol{z}_{t_{n+k}}, \boldsymbol{t}_{n+k}, \boldsymbol{t}_n, \boldsymbol{c}) - \omega\Psi(\boldsymbol{z}_{t_{n+k}}, \boldsymbol{t}_{n+k}, \boldsymbol{t}_n, \boldsymbol{\varnothing})$$
(17)

- For LCM, we use three possible ODE solvers here: DDIM (Song et al., 2020a), DPM-Solver (Lu et al., 2022a), DPM-Solver++ (Lu et al., 2022b), and we compare their performance in Sec 5.2.
- In fact, DDIM (Song et al., 2020a) is the first-order discretization approximation of the DPM-Solver (Proven in (Lu et al., 2022a)). Here we provide the detailed formula of the DDIM PF-ODE solver Ψ_{DDIM} from from t_{n+k} to t_n.

$$\Psi_{\text{DDIM}}(\boldsymbol{z}_{t_{n+k}}, t_{n+k}, t_n, \boldsymbol{c}) = \underbrace{\frac{\alpha_{t_n}}{\alpha_{t_{n+k}}} \boldsymbol{z}_{t_{n+k}} - \sigma_{t_n} \left(\frac{\sigma_{t_{n+k}} \cdot \alpha_{t_n}}{\alpha_{t_{n+k}} \cdot \sigma_{t_n}} - 1 \right) \hat{\boldsymbol{\epsilon}}_{\theta}(\boldsymbol{z}_{t_{n+k}}, \boldsymbol{c}, t_{n+k}) - \boldsymbol{z}_{t_{n+k}}$$
(18)

DDIM Estimated z_{t_n}

4.3 Accelerating Distillation with Skipping Time Steps

Pseudo-code for LCD with CFG and Skipping-Step techniques

- The modifications from the original Consistency Distillation (CD) algorithm in Song et al. (2023) are highlighted in blue.
- LCM sampling algorithm 3 is provided in Appendix B.

Algorithm 1 Latent Consistency Distillation (LCD)

Input: dataset \mathcal{D} , initial model parameter θ , learning rate η , ODE solver $\Psi(\cdot, \cdot, \cdot, \cdot)$, distance metric $d(\cdot, \cdot)$, EMA rate μ , noise schedule $\alpha(t), \sigma(t)$, guidance scale $[w_{\min}, w_{\max}]$, skipping interval k, and encoder $E(\cdot)$ Encoding training data into latent space: $\mathcal{D}_{z} = \{(z, c) | z = E(x), (x, c) \in \mathcal{D}\}$ $\theta^{-} \leftarrow \theta$ **repeat** Sample $(z, c) \sim \mathcal{D}_{z}, n \sim \mathcal{U}[1, N - k]$ and $\omega \sim [\omega_{\min}, \omega_{\max}]$ Sample $z_{t_{n+k}} \sim \mathcal{N}(\alpha(t_{n+k})z; \sigma^{2}(t_{n+k})\mathbf{I})$ $\hat{z}_{t_{n}}^{\Psi,\omega} \leftarrow z_{t_{n+k}} + (1 + \omega)\Psi(z_{t_{n+k}}, t_{n+k}, t_{n}, c) - \omega\Psi(z_{t_{n+k}}, t_{n+k}, t_{n}, \emptyset)$ $\mathcal{L}(\theta, \theta^{-}; \Psi) \leftarrow d(f_{\theta}(z_{t_{n+k}}, \omega, c, t_{n+k}), f_{\theta^{-}}(\hat{z}_{t_{n}}^{\Psi,\omega}, \omega, c, t_{n}))$ $\theta \leftarrow \theta - \eta \nabla_{\theta} \mathcal{L}(\theta, \theta^{-})$ $\theta^{-} \leftarrow \text{stopgrad}(\mu\theta^{-} + (1 - \mu)\theta)$ **until** convergence

4.4 Latent Consistency Fine-Tuning For Customized Dataset

Real Appendix C

- Stable Diffusion excel in diverse text-to-image generation tasks but often require fine-tuning on customized datasets to meet the requirements of downstream tasks.
- Propose Latent Consistency Fine-tuning (LCF), a fine-tuning method for pretrained LCM.
- Inspired by Consistency Training (CT) (Song et al., 2023), LCF enables efficient few-step inference on customized datasets without relying on a teacher diffusion model trained on such data.

Note that

- This method can also utilize the skippingstep technique to speedup the convergence.
- LCF is independent of the pre-trained teacher model, facilitating direct fine-tuning of a pre-trained LCM model without reliance on the teacher diffusion model

 Randomly select two time steps t_n and t_{n+k} that are k time steps apart and apply the same Gaussian noise ε to obtain the noised data z_{t_n}, z<sub>t_{n+k} as follows
</sub>

$$\boldsymbol{z}_{t_{n+k}} = \alpha(t_{n+k})\boldsymbol{z} + \sigma(t_{n+k})\boldsymbol{\epsilon} \quad , \quad \boldsymbol{z}_{t_n} = \alpha(t_n)\boldsymbol{z} + \sigma(t_n)\boldsymbol{\epsilon}.$$

• Directly calculate the consistency loss for these two time steps to enforce self-consistency property in Eq.4.

Algorithm 4 Latent Consistency Fine-tuning (LCF)

Input: customized dataset $\mathcal{D}^{(s)}$, pre-trained LCM parameter θ , learning rate η , distance metric $d(\cdot, \cdot)$, EMA rate μ , noise schedule $\alpha(t), \sigma(t)$, guidance scale $[w_{\min}, w_{\max}]$, skipping interval k, and encoder $E(\cdot)$

Encode training data into the latent space: $\mathcal{D}_z^{(s)} = \{(z, c) | z = E(x), (x, c) \in \mathcal{D}^{(s)}\}$ $\theta^- \leftarrow \theta$

repeat

Sample $(\boldsymbol{z}, \boldsymbol{c}) \sim \mathcal{D}_{\boldsymbol{z}}^{(s)}, n \sim \mathcal{U}[1, N - k]$ and $\boldsymbol{w} \sim [w_{\min}, w_{\max}]$ Sample $\boldsymbol{\epsilon} \sim \mathcal{N}(\boldsymbol{0}, \boldsymbol{I})$ $\boldsymbol{z}_{t_{n+k}} \leftarrow \alpha(t_{n+k})\boldsymbol{z} + \sigma(t_{n+k})\boldsymbol{\epsilon} , \quad \boldsymbol{z}_{t_n} \leftarrow \alpha(t_n)\boldsymbol{z} + \sigma(t_n)\boldsymbol{\epsilon}$ $\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\theta}^-) \leftarrow d(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{z}_{t_{n+k}}, t_{n+k}, \boldsymbol{c}, \boldsymbol{w}), \boldsymbol{f}_{\boldsymbol{\theta}^-}(\boldsymbol{z}_{t_n}, t_n, \boldsymbol{c}, \boldsymbol{w}))$ $\boldsymbol{\theta} \leftarrow \boldsymbol{\theta} - \eta \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\theta}^-)$ $\boldsymbol{\theta}^- \leftarrow \text{stopgrad}(\mu \boldsymbol{\theta}^- + (1 - \mu)\boldsymbol{\theta})$ until convergence

5. EXPERIMENT

 Employ latency consistency distillation to train LCM on two subsets of LAION-5B.

5.1 Text-to-Image Generation

Datasets

- LAION-5B (Schuhmann et al., 2022): LAION-Aesthetics-6+ (12M) and LAION-Aesthetics-6.5+ (650K) for text-to-image generation
- Consider two resolutions
- 512x512 resolution : Use LAION-Aesthetics-6+, which comprises 12M text-image pairs with predicted aesthetics scores higher than 6.
- 768x768 resolution : Use LAION-Aesthetics-6.5+, with 650K textimage pairs with aesthetics score higher than 6.5.

Model Configuration

- 512x512 resolution : Use the pre-trained Stable Diffusion-V2.1-Base (Rombach et al., 2022) as the teacher model, which was originally trained on resolution 512×512 with ε-Prediction (Ho et al., 2020).
- 768x768 resolution : Use the widely used pre-trained Stable Diffusion-V2.1, originally trained on resolution 768×768 with v-Prediction (Salimans & Ho, 2022).
- Train LCM with 100K iterations and a batch size of 72 for (512 \times 512) setting, and 16 for (768 \times 768) setting, the same learning rate 8e-6 and EMA rate μ = 0.999943 as used in (Song et al., 2023).
- For augmented PF-ODE solver Ψ and skipping step k in Eq. 17,
 - Use DDIM-Solver (Song et al., 2020a) with skipping step k = 20.
 - Set the guidance scale range $[\omega_{\min}, \omega_{\max}] = [2,14]$, consistent with (Meng et al., 2023)

5.1 Text-to-Image Generation

Baselines

- Baselines : DDIM (Song et al., 2020a), DPM (Lu et al., 2022a), DPM++ (Lu et al., 2022b), Guided-Distill (Meng et al., 2023)
- DDIM, DPM, DPM++ : Taining-free samplers requiring more peak memory per step with classifier-free guidance.
- Guided-Distill : Requires two stages of guided distillation. Due to the limited resource (Meng et al. (2023) used a large batch size of 512, requiring at least 32 A100 GPUs), reduce the batch size to 72 and trained for the same 100K iterations.
- LCM achieves faster convergence and superior results under the same computation cost.

Evaluation

- Generate **30K images** from **10K text prompts** in the test set (3 images per prompt)
- Adopt FID and CLIP scores to evaluate the diversity and quality of the generated images.
- Use ViT-g/14 for evaluating CLIP scores

5.1 Text-to-Image Generation

Results

Model (512 \times 512) Reso	FID↓				CLIP Score ↑			
	1 Step	2 STEPS 4	4 Steps	8 Steps	1 Steps	2 Steps	4 STEPS	8 STEPS
DDIM (Song et al., 2020a)	183.29	81.05	22.38	13.83	6.03	14.13	25.89	29.29
DPM (Lu et al., 2022a)	185.78	72.81	18.53	12.24	6.35	15.10	26.64	29.54
DPM++ (Lu et al., 2022b)	185.78	72.81	18.43	12.20	6.35	15.10	26.64	29.55
Guided-Distill (Meng et al., 2023)	108.21	33.25	15.12	13.89	12.08	22.71	27.25	28.17
LCM (Ours)	35.36	13.31	11.10	11.84	24.14	27.83	28.69	28.84

Table 1: Quantitative results with $\omega = 8$ at 512×512 resolution. LCM significantly surpasses baselines in the 1-4 step region on LAION-Aesthetic-6+ dataset. For LCM, DDIM-Solver is used with a skipping step of k = 20.

Model (768 \times 768) Reso	FID↓				CLIP SCORE ↑				
	1 STEP 2	2 Steps 4	STEPS	8 Steps	1 Steps	2 STEPS	4 Steps	8 STEPS	
DDIM (Song et al., 2020a)	186.83	77.26	24.28	15.66	6.93	16.32	26.48	29.49	
DPM (Lu et al., 2022a)	188.92	67.14	20.11	14.08	7.40	17.11	27.25	29.80	
DPM++ (Lu et al., 2022b)	188.91	67.14	20.08	14.11	7.41	17.11	27.26	29.84	
Guided-Distill (Meng et al., 2023)	120.28	30.70	16.70	14.12	12.88	24.88	28.45	29.16	
LCM (Ours)	34.22	16.32	13.53	14.97	25.32	27.92	28.60	28.49	

Table 2: Quantitative results with $\omega = 8$ at 768×768 resolution. LCM significantly surpasses the baselines in the 1-4 step region on LAION-Aesthetic-6.5+ dataset. For LCM, DDIM-Solver is used with a skipping step of k = 20.

- DDIM, DPM, DPM++ require more peak memory per sampling step with CFG
- LCM requires only one forward pass per sampling step, saving both time and memory.
- Guided-Distill : two-stage distillation
 procedure
- LCM : one-stage guided distillation, which is much simpler and more practical.

5.1 Text-to-Image Generation

Results

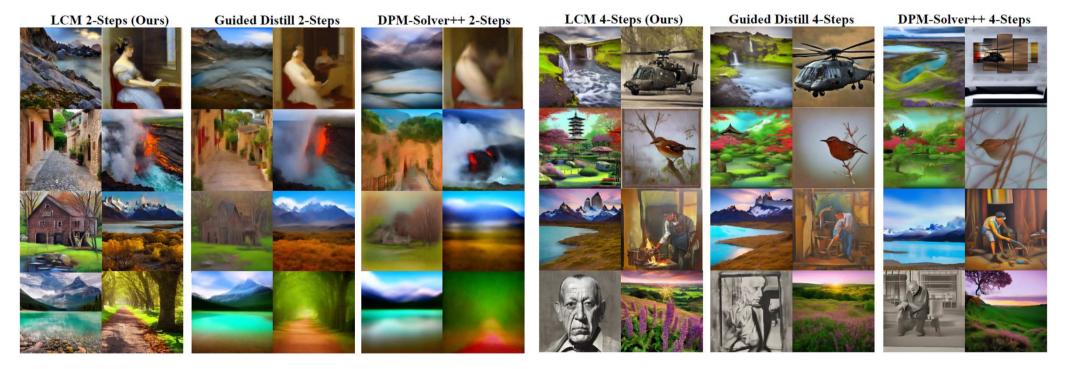
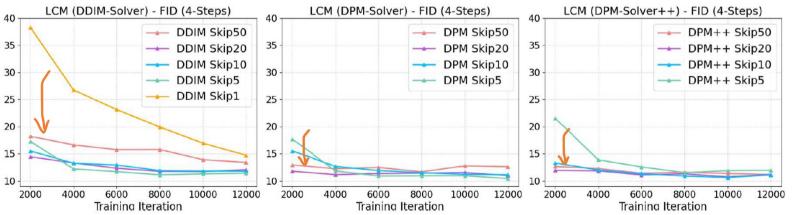


Figure 2: Text-to-Image generation results on LAION-Aesthetic-6.5+ with 2-, 4-step inference. Images generated by LCM exhibit superior detail and quality, outperforming other baselines by a large margin.

5.2 Ablation Study

- > ODE Solvers & Skipping-Step Schedule
- Compare various solvers Ψ (DDIM, DPM, DPM++ for solving the augmented PF-ODE specified in Eq 17, and explore different skipping step schedules with different k.
- 1) Using **SKIPPING-STEP** techniques (see Sec 4.3), LCM achieves fast convergence within **2,000 iterations** in the **4-step** inference setting.
- 2) DPM and DPM++ solvers perform better at a larger skipping step (k = 50) compared to the DDIM solver which suffers from increased ODE approximation error with larger k.
- 3) Very small k values (1 or 5) result in slow convergence and very large ones (e.g., 50 for DDIM) may lead to inferior results



 We choose k = 20, which provides competitive performance for all three solvers.

Figure 3: Ablation study on different ODE solvers and skipping step k. Appropriate skipping step k can significantly accelerate convergence and lead to better FID within the same number of training steps.

5.2 Ablation Study

- \succ The Effect of Guidance Scale ω
- Examine the effect of using different CFG scales ω in LCM.
- ω balances sample quality and diversity
 - A larger ω generally tends to improve sample quality (indicated by CLIP), but may compromise diversity (measured by FID).
 - \checkmark An increased ω yields better CLIP scores at the expense of FID.

- 1) Using large ω enhances sample quality (CLIP Scores) but results in relatively inferior FID.
- The performance gaps across 2, 4, and 8 inference steps are negligible, highlighting LCM's efficacy in 2~8 step regions. However, a noticeable gap exists in one-step inference.

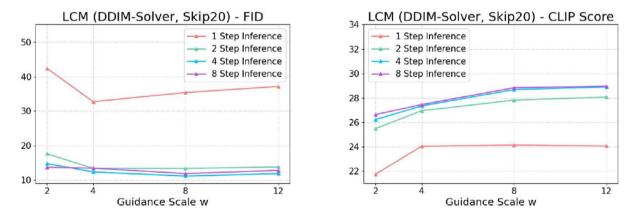


Figure 4: Ablation study on different classifier-free guidance scales ω . Larger ω leads to better sample quality (CLIP Scores). The performance gaps across 2, 4, and 8 steps are minimal, showing the efficacy of LCM.

5.2 Ablation Study

ightarrow The Effect of Guidance Scale ω

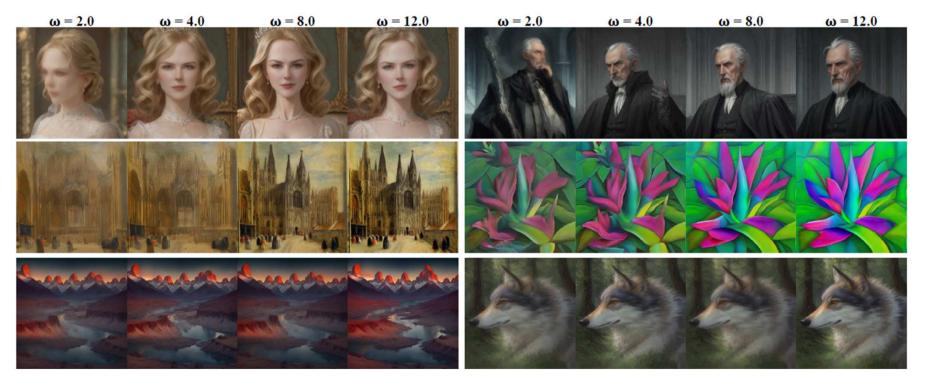


Figure 5: 4-step LCMs using different CFG scales ω . LCMs utilize one-stage guided distillation to directly incorporate CFG scales ω . Larger ω enhances image quality.

A larger ω enhances sample quality, verifying the effectiveness of our one-stage guided distillation method.

5.3 Downstream Consistency Fine-tuning Results

- 2 customized image datasets, Pokemon dataset (Pinkney, 2022) and Simpsons dataset (Norod78, 2022), that 90% is used for finetuning and the rest 10% for testing.
- Origin LCM
 IK Finetuning
 10K Finetuning
 30K Finetuning
 Origin LCM
 IK Finetuning
 10K Finetuning
 30K Finetuning

 Image: Structure Structure
- Figure 6: 4-step LCMs using Latent Consistency Fine-tuning (LCF) on two customized datasets: Pokemon Dataset (left), Simpsons Dataset (right). Through LCF, LCM produces images with customized styles.

• For LCF, we utilize pretrained LCM that was originally trained at the

LCM for **30K iterations** with a learning rate 8e-6.

resolution of 768 × 768 used in Table 2. We fine-tune the pre-trained